Decoding the neural representations of digital humans' emotional faces in stereo- versus monoscopic viewing conditions – a study plan

This

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Introduction

facial expressions Emotional are а cornerstone of social communication. Virtual **Reality** (VR) technology and **digital humans** offer new possibilities to study these processes in more lifelike yet highly controlled settings. One core feature of VR is that it allows for **stereoscopic** viewing conditions. Stereoscopic information can facilitate face recognition [1] and assists the construction of robust facial representations in memory [2]. Such enriched mental representations could be due to additional visual features in stereoscopic viewing conditions or because of increased relevance of more lifelike stimuli.

Combining EEG with multivariate decoding has been suggested as a sensitive approach to study the neurophysiological underpinnings of face processing [3].

If enriched mental representations manifest in better separable neurophysiological activation patterns (e.g., due to a higher number of represented features), this could be reflected in a higher decoding performance in the according experimental conditions.

Main Hypotheses

- H1: The emotional expressions of **computer**generated human faces can be decoded from the EEG of an observer in a virtual reality setup.
- H2: The **decoding performance** is **significantly** higher under stereoscopic as compared to monoscopic viewing conditions.

References

Please visit this link for a list of the cited resources:



https://tinyurl.com/ VRstereofem-**Poster-MBBS**



4. Fraunhofer Institute Heinrich Hertz, Department of Artificial Intelligence, Berlin, Germany

Experimental Paradigm

Participants:

N = **30** (all females, 18-40 years) Tested for **stereopsis (stereo fly test)** 720 trials in 6 blocks



Stimuli: Different renderings of digital humans' emotional facial expressions in mono- and stereoscopic viewing conditions (Figure 1)

Facial emotion recognition task (Figure 2) Control measure: Subjective rating of the perceived **intensity** of the stimulus' facial emotion (Self-Assessment Manikins)

Stimuli Happy Surprise Neutral Angry

Emotions



Figure 1: Manipulated features of the stimulus





500ms 1sec Till response or 5 sec 1sec **Display time duration** Intertrial Selection Stimulus ixation cross Interval NEUTRAL HAPPY ANGRY OTHER + SURPRISED [7] se the emotion exp by the fac 720 Trials

Figure 2: Schematic diagram of experimental paradigm

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Analysis Main Manipulation Both viewing conditions are presented in a VR headset Raw c Monoscopic Stereoscopic The 3D object is captured with a Two (virtual) cameras Filteri single (virtual) camera and the (one per eye) record a resulting 2D image is presented 3D object with slightly as a plane in the virtual different perspectives. Epocł environment (comparable to the creates showing a picture on a screen). impression of spatial The visual input to both eyes is depth. therefore identical. Baseli Correct Data clea Stimuli were generated using the FACSHuman [4] plugin for MakeHuman [5]. Emotions are computer generated according to the FACS Decod [6] with 100% intensity and have recently been validated [4]. Total of three identities and four facial expressions (neutral, happy, angry and surprise) To ensure central presentation of the stimuli, the content is fixed to the participant's viewpoint. Statisti Stimuli are shown in a random sequence with all analys experimental conditions interleaved. (group le **Experimental Setup** Hardware: **HTC Vive Pro Eye headset** (rf: 90Hz) incl. a Tobii eye-tracker (120Hz) 60 active EEG electrodes (10/20) BrainProducts LiveAmp (500Hz) Software: Potentia Unity 3D (v2020.3.3) FACSHuman plugin [4] MakeHuman (v1.2.0) [5] Unity Experiment Framework **Control measures:** <u>(v2.3.4)</u>[6]

Lab Streaming Layer (LSL)



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ta	Data analysis will be implemented using MNE-Python (v24.0) [8] and R (v4.0.0) [9].
g	 Band pass filter: 0.1-40Hz
	 Relative to stimulus onset -0.3-1.0s
	 Filter (1-40Hz) + epoch a copy of the data Reject bad epochs (autoreject [10]) Picard algorithm [11] Reject components correlated with EOG Apply ICA weights to regular epochs
e on	 Mean activity of 0.2s pre-stimulus
ning	 Using autoreject (local) [10] Locally interpolate bad channels Reject bad epochs
ng	 Logistic regression (multiclass, one-vs-one) Decoding target: emotional expression L2 regularization Sliding window (20ms, no overlap) Features: Mean activation per channel Mini-batches: average of 3 trials 3-fold cross-validation (20 repetitions)
al s /el)	 Time windows of interest: 0.08-0.12s (P1) 0.14-0.20s (N170) 0.15-0.35s (EPN) 0.40-0.60s (LPC) Hypothesis 1: t-test mean classification performance against empirical chance level (null distribution: rep. permute labels) Hypothesis 2: Compare (t-test) mean classification performance in mono- vs. stereoscopic viewing conditions
Challenge: Eye Movements	

Saccades lead to fixation-related EEG potentials [12] Systematic differences in saccade statistics between the exp. conditions might influence the classifier performance

- Compare saccade statistics
- Run classifier on eye-tracking data & compare results
- Isolate saccade-related components via deconvolution [13]