Parametric Working Memory Coding **During Motor Preparation**

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INTRODUCTION

Parametric sensory working memory content has been extensively studied in recent years (e.g. Romo et al., 1999, Schmidt et al., 2017).

It has been shown using multivoxel pattern analysis (MVPA) that these representations are maintained in the right inferior prefrontal cortex (and premotor areas) during the working memory period (*e.g.* Wu *et al.*, 2020).

RESULTS

Participants (N=14) managed to **Figure 2** perform the challenging task. The applied grip-force was in the target range on average in 55% of trials. Violin plots in Figure 2A display the distribution of responses in terms of applied force on the hand-grip device for the respective trial types. We further ensured that participants did not apply force during the *delay period* (see Figure 2A, lower display). For the fMRI analysis all trials were included where the applied force was within the target range \pm 20°, resulting in the inclusion of overall 70% of trials.

A. Behavioural performance



- The question of whether similar parametric representations can also be found for the retainment of simple movement parameters as the strength of handgrips during the working memory delay period has not yet been investigated.
- Our hypothesis is that gradual representations of movement parameters can be decoded from effector-specific brain areas, such as the motor and premotor cortex, parietal brain areas, and supplementary motor areas.

METHODS

Figure 1



Figure 3

A. SVR Decoding of retained grip-force

















In an fMRI experiment, participants performed a delayed grip force task. Each trial (illustrated in **Figure 1A**) started with the presentation of a *strength-indicator*, which represents two of four possible force levels as coloured slices (their colours were either cyan or blue). A retro cue indicating which of two levels of grip-force had to be maintained during a subsequent *delay period* of 9 seconds. Participants performed the hand squeezing task upon display of a pre-Go (0.5 s) and a Go-cue. *Feedback* was provided by showing if the applied force was correct. Grip force was assessed by a non-magnetic grip-force transducer (Current Designs, HHSC-1x1-GRFC-V2). For illustration of the applied grip force within a trial see Figure 1B. fMRI Data was acquired in four functional runs à 18.30min with an EPI sequence (64 channel head coil, 37 slices, TR= 1.5 sec, 2.5x2.5x2.5 voxels) on a 3T Siemens Prisma fit at the *Center for Cognitive Neuroscience Berlin* (CCNB).

We applied a multivoxel pattern analysis (MVPA) searchlight (r=3voxel) approach to test which brain regions exhibited multivariate parametric WM codes of gripforce preparation during the *delay period*. Preprocessing was limited to realignment; Beta-estimates of a finite impulse response model (each of the four trial types across the 9s WM delay and 6 consecutive time bins; Figure 1C) were entered to a four-fold cross-validated support vector regression (SVR) decoding schema as implemented in The Decoding Toolbox (Hebart *et al.*, 2015). We applied a time resolved approach, namely performing a decoding analysis within every time-bin of the delay phase (e.g., Schmidt *et al.* 2017)

To test for regions that exhibit above chance decoding during the delay phase, we computed t-contrast across the WM phase for every time bin. The preliminary group-level analysis with 14 participants revealed a network comprised of dorsal pre-motor cortex (PMd), supplementary motor area (SMA), and bilateral superior parietal regions, as shown in Figure 3A at p<0.05 FWE corrected. Time courses of the evolution of prediction accuracy of the applied SVR approach across the *delay period* and response phase are displayed (green). Performing the same analysis on the non-prepared compression strength (grey) does not reveal above chance decoding (as shown in Figure 3B). There is a strong increase in the decoding accuracy in the primary motor cortex when the motor response was given (Figure 3C).

CONCLUSION

These results extend the current literature on parametric WM representing by showing a distributed network of effector-related brain areas to

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contribute to the graded representation of the preparation of grip-forces with different strength.

This preliminary evidence is in line with previous studies (Wu et al., 2020), which suggest that besides the performance of concrete actions, the PMC could also contribute to the maintenance of more abstract representations necessary to prepare future actions.